

# Multi-Organ Segmentation using Vantage Point Forests and Binary Context Features

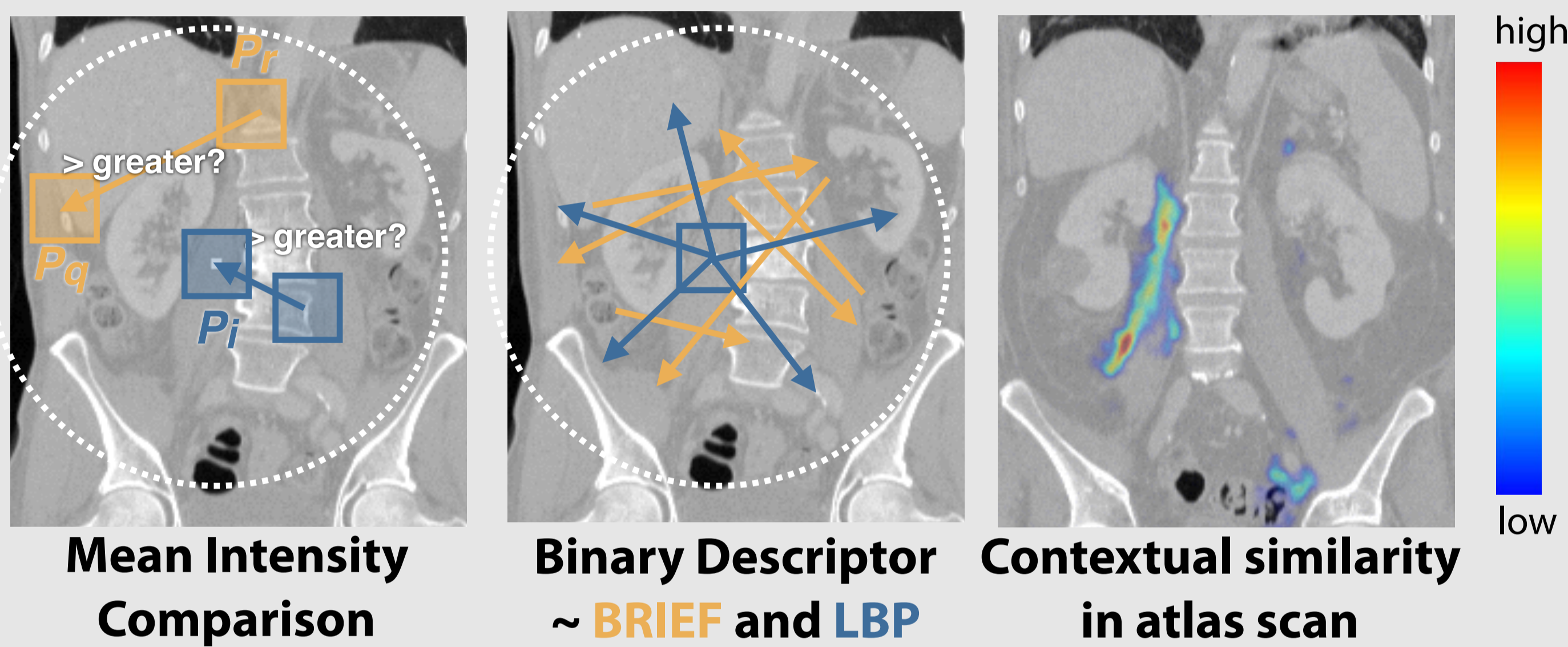
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## Highlights / Contributions

- **Accurate CT multi-organ segmentation:** Dice 84-88%
- Run-times of **few seconds** on single CPU
- **Overcome** limitations of **axis-parallel** splits in decision trees
- Novel highly efficient classifier: **Vantage Point Forest**
- **Source-code** available: <http://mpheinrich.de/research.html#vpg>

## 1. Binary Contextual Descriptors

- Combines several weak mean pixel intensity comparisons
- Fixed random sampling layout (640 pairs) in neighbourhood
- **Highly discriminative binary descriptor  $h_i$**



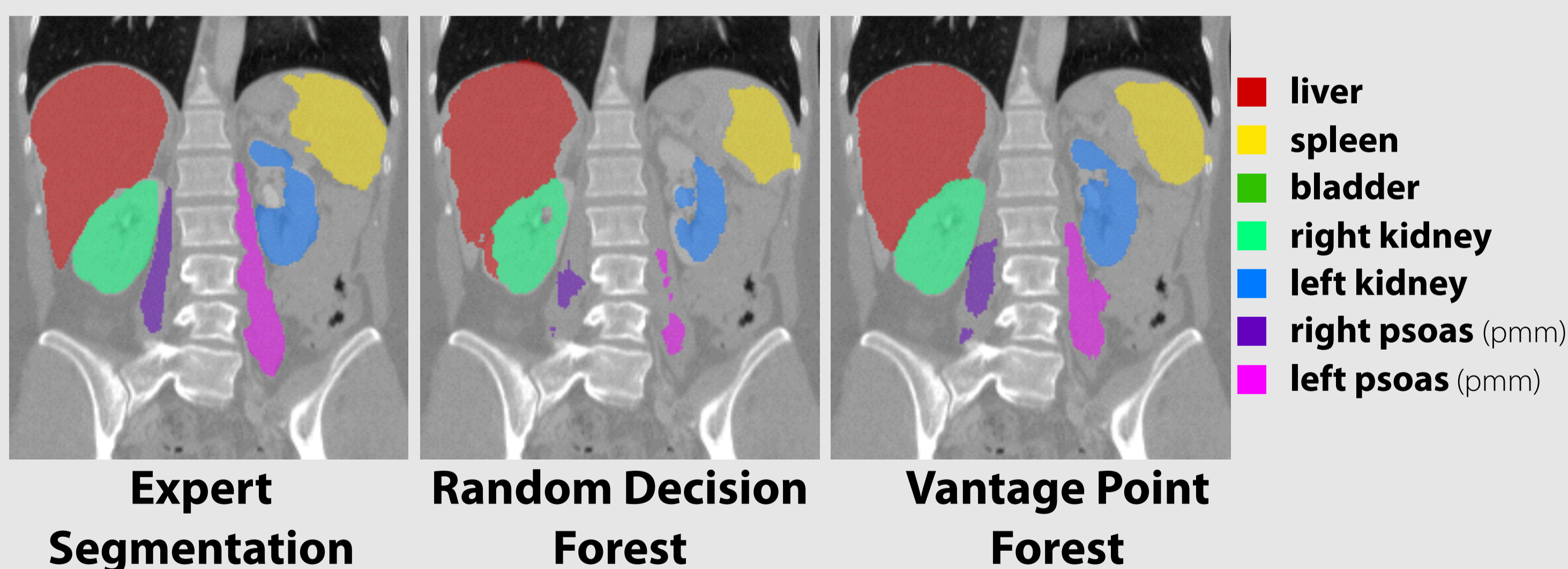
## Hamming Distance between descriptors

- Counting number of dissimilar bits (popcount)
- **Orders of magnitudes faster** than mutual info. / SSD

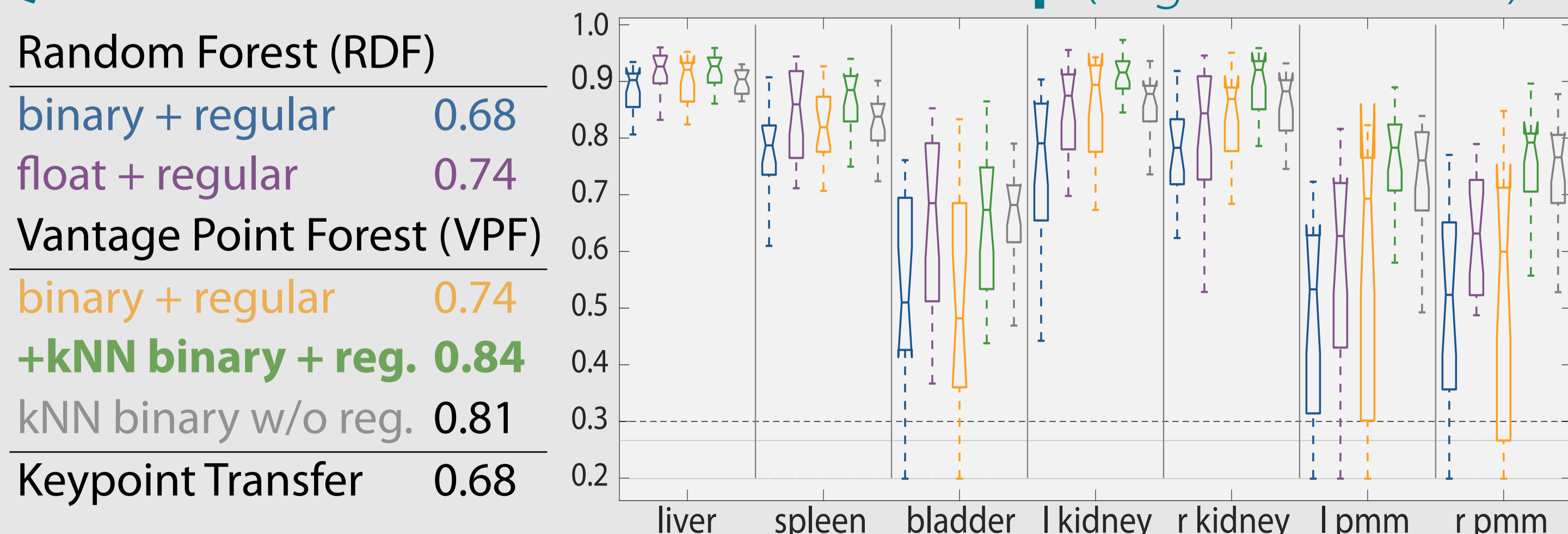
## 4. Experiments and Results

### VISCERAL Anatomy 3 Dataset<sup>1</sup>

- 20+10 abdominal ceCT scans / Evaluation on 7 organs



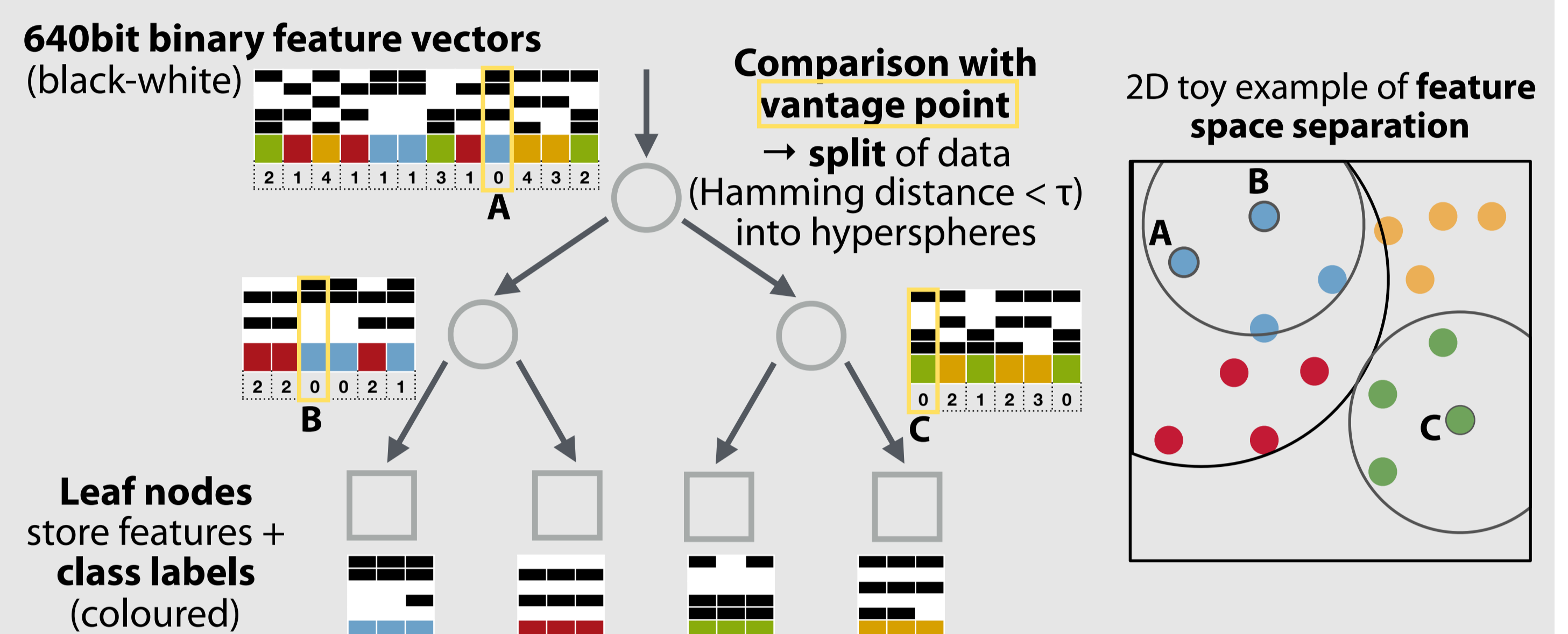
### Quantitative Evaluation of Dice Overlap (avg. w/o bladder)



→ improved Dice by 10% against best RDF variant

## 2. Vantage Point Forest

- **Split function based on Hamming distance** of full-length descriptor between sample and vantage point



VP tree originally introduced for clustering of real-valued data in 1993<sup>2</sup>

1. randomly **pick vantage point** from all samples at current node
2. **calculate Hamming distance** of VP to all other samples
3. sort by distance and **split data into left and right child nodes**  
alternative split criteria employing class labels possible
4. **recursively repeat** 1.-3. until specified leaf size is reached

### Ensemble of Vantage Point Trees

- **Improved generalisation:** randomisation at VP selection
- **Retrieve samples** from leaf nodes **of all trees** (in test):  
+ **linear kNN search** for higher accuracy (cache-efficient)
- **Higher performance** than state-of-art **approximate kNN**
- Fast training of oblique decision trees (15 sec for forest)

## 3. Regularisation with Multilabel Random Walk

Upsample and refine probabilistic output (edge-preserving)

$$\sum_{\mathbf{x}} \frac{1}{2} (P(\mathbf{x})^y - P(\mathbf{x})_{reg}^y)^2 + \sum_{\mathbf{x}} \frac{\lambda}{2} \|\nabla P(\mathbf{x})_{reg}^y\|^2$$

Fast implementation of successive-overrelaxation solver

## Outlook / Future Work

- VP Regression Forest for landmark localisation<sup>3</sup>
- General purpose approx. kNN for retrieval / image registration
- Learning of problem specific feature selection + multiple stages

## Literature

- (1) Jiménez-del-Toro et al.: "Cloud-based Evaluation of Organ Segmentation and Landmark Detection Algorithms: VISCERAL Anatomy Benchmarks" IEEE Trans Medical Imaging 2016
- (2) Yianilos: "Data structures and algorithms for nearest neighbor search in general metric spaces" ACM SIAM 1993
- (3) Heinrich, Oktay: "Accurate Intervertebral Disc Localisation and Segmentation in MRI using Vantage Point Hough Forests and Multi-Atlas Fusion" MICCAI Computational Methods and Clinical Applications for Spine Imaging 2016

